Recall this version of the PCP theorem from last lecture.
Theorem 1. There exists an alphabet $\Sigma$ and a constant $\varepsilon>0$ for which the following task is NPhard: Given a satisfiable 2CSP instance over $\Sigma$, find an assignment that satisfies a $1-\varepsilon$ fraction of constraints.

In a general 2CSP instance, a variable may be present in an arbitrary number of constraints. What if we restrict our attention to instances where every variable appears in at most $d$ constraints, where $d$ is small compared to the number of variables? When $d=1$, every variable appears in one constraint and finding a satisfying assignment is easy. When $d=2$, the task is a bit harder but still solvable in time linear in $n$. On the other hand, when $d$ is as large as the number of constraints the problem becomes NP-hard. This suggests that the problem may become gradually harder as $d$ gets larger.

It turns out that this intuition is incorrect:
Theorem 2. There exists an alphabet $\Sigma$ and constants $d$ and $\varepsilon$ such that given a satisfiable 2CSP instance over $\Sigma$ where every variable appears in at most d constraints, it is NP-hard to satisfy a $1-\varepsilon$ fraction of the constraints.

We prove this statement by reduction from Theorem 1. Let $\Phi$ be the 2CSP instance in question. We want to construct a new instance $\Phi^{\prime}$ which is as hard as $\Phi$, but every variable appears in at most $d$ constraints. Some of the variables in $\Phi$ may appear in more constraints. If variable $x_{i}$ appears in $n_{i}$ different constraints it is natural to replace it with $n_{i}$ new variables $x_{i 1}^{\prime}, \ldots, x_{i n_{i}}^{\prime}$ and impose some additional constraints that force all of $x_{i 1}^{\prime}, \ldots, x_{i n_{i}}^{\prime}$ to take the same value.
The first thing we may try is to add the constraints $x_{i 1}^{\prime}=x_{i 2}^{\prime}, x_{i 2}^{\prime}=x_{i 3}^{\prime}, \ldots, x_{i\left(n_{i}-1\right)}^{\prime}=x_{i n_{i}}^{\prime}$ to $\Phi^{\prime}$. Then if $\Phi$ has a satisfying assignment, the assignment obtained by setting $x_{i 1}^{\prime}=\cdots=x_{i n_{i}}^{\prime}=x_{i}$ will be satisfying for $\Phi^{\prime}$. Suppose that we could then find an assignment $x^{\prime}$ that satisfies a $1-\varepsilon^{\prime}$ fraction of its constraints of $\Phi^{\prime}$. Can we use $x^{\prime}$ to obtain an assignment that satisfies most constraints in $\Phi$ ?

It is not hard to see that if $\varepsilon^{\prime}=0$, the assignment $x_{i}=x_{i 1}^{\prime}=\cdots=x_{i n_{i}}^{\prime}$ is satisfying for $\Phi$. However, even if one of the equality constraints is violated, the values of $x_{i j}^{\prime}$ could split into two equally sized sets. Then it is not clear which value to assign to $x_{i}$ and it is possible to come up with examples where no matter which value we assign, a large fraction of the constraints of $\Phi$ will be violated.

So we need to make the equality constraints more robust: If there is no clear majority among the values $x_{i 1}^{\prime}, \ldots, x_{i n_{i}}^{\prime}$, then not one but many of the equality constraints should be violated. One way to do so is to impose the equality constraint $x_{i j}^{\prime}=x_{i j^{\prime}}^{\prime}$ for every pair $j<j^{\prime}$; but then we have done nothing about reducing the number of constraints a variable appears in.

In general the equality constraints we are looking for can be described by an undirected graph $G$ on the vertices $\{1, \ldots, t\}$. An assignment to $x_{i 1}^{\prime}, \ldots, x_{i n_{i}}^{\prime}$ can be viewed as a partition of the vertices into sets $A_{\sigma}=\left\{j: x_{i j}^{\prime}=\sigma\right\}$, where $\sigma$ ranges over $\Sigma$. On the one hand, we want the degree of this graph to be constant. On the other hand, we want that a partition $\left\{A_{\sigma}\right\}$ splits many of the edges of $G$, unless one of the sets $A_{\sigma}$ contains most of the vertices.

Both of these properties are achieved by expander graphs. To understand expander graphs and their properties we first need to take a detour into random walks, adjacency matrices, and eigenvalues.

In what follows we will assume the graph $G$ is undirected, connected, and $d$-regular.

## 1 Adjacency matrix and eigenvalues

Suppose a particle sits at a vertex $s$ of some graph $G$. At every step, $s$ moves to a random one of its neighbors. How long will it take $s$ to reach a vertex in $G$ that looks random and independent of $s$ ?

To answer this question, it will be helpful to represent the random walk by a sequence of probability distributions $\mathbf{p}^{0}, \mathbf{p}^{1}, \ldots$ on the vertices of $G$, with the following interpretation: At each step $t, \mathbf{p}^{t}(u)$ is the probability of the particle ending up at vertex $u$ after $t$ steps of the walk. Initially, we have $\mathbf{p}^{0}$ assign probability 1 to vertex $s$, and probability 0 to all the other vertices. The distribution $\mathbf{p}^{t+1}$ can be calculated from $\mathbf{p}^{t}$ via the formula

$$
\begin{equation*}
\mathbf{p}^{t+1}(u)=\sum_{v:(v, u) \text { is an edge }} \frac{1}{d} \cdot \mathbf{p}^{t}(v) . \tag{1}
\end{equation*}
$$

We are now interested in the following question: When $t$ gets large, how close does the distribution $\mathbf{p}^{t}$ get to the uniform distribution $\mathbf{u}$ on the set of vertices? To answer this question, we need some way of measuring how "close" two distributions are. In our setting the most convenient measure is the $\ell_{2}$ norm. The $\ell_{2}$ norm of a vector $\mathbf{v}$ is the quantity

$$
\|\mathbf{v}\|=\left(\sum_{i} \mathbf{v}_{i}^{2}\right)^{1 / 2}
$$

and the $\ell_{2}$ distance between two vectors $\mathbf{v}$ and $\mathbf{v}^{\prime}$ is the $\ell_{2}$ norm of $\mathbf{v}-\mathbf{v}^{\prime}$. We will think of probability distributions as vectors in $\mathbb{R}^{n}$ (with one entry for each vertex in the graph), and we will say that two distributions $\mathbf{p}$ and $\mathbf{p}^{\prime}$ are $\epsilon$-close (in $\ell_{2}$ distance) if $\left\|\mathbf{p}-\mathbf{p}^{\prime}\right\| \leq \epsilon$.
The (normalized) adjacency matrix of $G$ is an $n \times n$ matrix $A$ defined as follows:

$$
A_{u, v}=\frac{\text { number of edges between } u \text { and } v \text { in } G}{d}
$$

This matrix is symmetric and the entries in each row add up to one. Using $A$, we can write equation 1 in matrix form as $\mathbf{p}^{t+1}=\mathbf{p}^{t} A$ (it is customary to represent $\mathbf{p}^{t}$ as row vectors) and so we immediately obtain that $\mathbf{p}^{t}=\mathbf{p}^{0} A^{t}$.

The eigenvalues and eigenvectors of $A$ play a significant role in determining the behavior of random walks on $G$. Recall that an eigenvalue-eigenvector pair is a complex number $\lambda$ and a vector $\mathbf{v}$ such that $\mathbf{v} A=\lambda \mathbf{v}$. It is a basic theorem in linear algebra that symmetric matrices have an orthonormal basis of eigenvectors with real eigenvalues. Let's denote these pairs by $\left(\lambda_{1}, \mathbf{v}_{1}\right), \ldots,\left(\lambda_{n}, \mathbf{v}_{n}\right)$ where $\lambda_{1} \geq \lambda_{2} \geq \ldots \geq \lambda_{n}$. (Some of the $\lambda_{i}$ may be negative.)
What is the meaning of this? Initially the position of our particle is determined by the distribution $\mathbf{p}^{0}$. Since the vectors $\mathbf{v}_{1}, \ldots, \mathbf{v}_{n}$ form an orthonormal basis we can decompose $\mathbf{p}^{0}$ in the form

$$
\mathbf{p}^{0}=\alpha_{1} \mathbf{v}_{1}+\cdots+\alpha_{n} \mathbf{v}_{n}
$$

where $\alpha_{i}=\left\langle\mathbf{p}^{0}, \mathbf{v}_{i}\right\rangle$ and $\alpha_{1}^{2}+\cdots+\alpha_{n}^{2}=1$.
After one step of the random walk, the distribution becomes

$$
\mathbf{p}^{1}=\mathbf{p}^{0} A=\alpha_{1} \mathbf{v}_{1} A+\cdots+\alpha_{n} \mathbf{v}_{n} A=\alpha_{1} \lambda_{1} \mathbf{v}_{1}+\cdots+\alpha_{n} \lambda_{n} \mathbf{v}_{n}
$$

and after $t$ steps

$$
\begin{equation*}
\mathbf{p}^{t}=\mathbf{p}^{0} A^{t}=\alpha_{1} \lambda_{1}^{t} \mathbf{v}_{1}+\cdots+\alpha_{n} \lambda_{n}^{t} \mathbf{v}_{n} \tag{2}
\end{equation*}
$$

Let's think of what happens when $t$ becomes large. We will assume the values $\alpha_{i}$ are nonzero since the initial position of the particle can be arbitrary. ${ }^{1}$ Eventually the right hand side of the expression will be dominated by the term in which $\lambda_{i}$ has largest absolute value; this is either $\left|\lambda_{1}\right|$ or $\left|\lambda_{n}\right|$. This absolute value cannot exceed 1 , because $\mathbf{p}^{t}$ would then become very large, but its norm is bounded since it is a probability distribution. Similarly, the absolute value cannot be less than 1 because then $\mathbf{p}^{t}$ would become very small when $t$ gets large. Finally, the largest $\lambda_{i}$ in absolute value cannot be -1 , because $\mathbf{p}^{t}$ would then eventually be shifting signs; since it is a vector of probabilities, its entries must always be nonnegative.

Therefore, it must be the case that $\lambda_{1}=1$, and

$$
\max \left\{\left|\lambda_{i}\right|: 2 \leq i \leq n\right\}=\max \left(\lambda_{2},-\lambda_{n}\right) \leq 1 .
$$

The quantity on the left side is denoted by $\lambda=\lambda(G)$ and plays a very important role. Because $\mathbf{u} A=\lambda_{1} \mathbf{u}$, so the eigenvector $\mathbf{v}_{1}$ associated to $\lambda_{1}=1$ equals $\sqrt{n} \cdot \mathbf{u}$. Now from (2) we have that

$$
\left\|\mathbf{p}^{t}-\alpha_{1} \mathbf{v}_{1}\right\|^{2}=\alpha_{2}^{2} \lambda_{2}^{2 t}+\cdots+\alpha_{n}^{2} \lambda_{n}^{2 t} \leq \lambda^{2 t} .
$$

The left hand side has a natural interpretation. Recall that $\alpha_{1}=\left\langle\mathbf{p}^{0}, \mathbf{v}_{1}\right\rangle=1 / \sqrt{n}$, so $\alpha_{1} \mathbf{v}_{1}$ equals the uniform distribution $\mathbf{u}$. Thus $\lambda^{t}$ measures how close $\mathbf{p}^{t}$ gets to the uniform distribution after $t$ steps of the walk:

$$
\begin{equation*}
\left\|\mathbf{p}^{t}-\mathbf{u}\right\| \leq \lambda^{t} \tag{3}
\end{equation*}
$$

Another way of saying this is that $\lambda$ determines the rate at which $\mathbf{p}^{t}$ converges to the uniform distribution: The smaller $\lambda$ is, the faster we will get to a uniformly random vertex.

## 2 Expander graphs

To get some intuition about equation (3), notice that in $t$ steps the particle can reach at most $1+(d-1)+\cdots+(d-1)^{t} \leq(d-1)^{t+1}$ vertices of the graph. This value is attained when the $t$-neighborhood of $s$ is a $d$-regular tree. Let $t$ be the largest value for which $(d-1)^{t+1}$ is at most $n / 2$. Then at least half the entries of $\mathbf{p}^{t}$ are zero and

$$
\lambda^{t} \geq\left\|\mathbf{p}^{t}-\mathbf{u}\right\| \geq\left(n / 2 \cdot(0-1 / n)^{2}\right)^{1 / 2}=\frac{1}{\sqrt{2 n}} \geq \frac{1}{\sqrt{2(d-1)^{t+2}}}
$$

from where $\lambda \geq(1 / \sqrt{d-1}) \cdot\left(2(d-1)^{2}\right)^{-1 / 2 t}$. As $n$ gets larger, the second term approaches 1 and $\lambda$ must be at least as large as $1 / \sqrt{d-1}$.

A more precise analysis shows that for every graph, $\lambda \geq 2 \sqrt{d-1} / d-o_{n}(1)$, where $o_{n}(1)$ is quantity that converges to zero as $n$ gets large. There exist graphs such that $\lambda=2 \sqrt{d-1} / d$ for infinitely many values of $n$. Such graphs are called Ramanujan graphs. ${ }^{2}$

[^0]For our purposes, it will be enough to consider graph families for which as $n$ grows, $\lambda$ stays bounded away from one. If this is the case, then after only $t=\Theta(\log n)$ steps of the random walk, we have that

$$
\begin{equation*}
\left\|\mathbf{p}^{t}-\mathbf{u}\right\| \leq \lambda^{\Theta(\log n)}=n^{-\Theta(1)} \tag{4}
\end{equation*}
$$

so $\mathbf{p}^{t}$ gets very close to the uniform distribution, and in fact all vertices of $G$ are reached with probability $1 / n \pm o(1 / n)$ for the correct choice of $\Theta(\cdot)$ constant.
Definition 3. A family of graphs $\left\{G_{n}\right\}$, where $G_{n}$ has $n$ vertices and is $d$-regular, is called an expander family if there is a constant $\epsilon>0$ such that $\lambda\left(G_{n}\right) \leq 1-\epsilon$ for every sufficiently large $n$.

## 3 Edge expansion

Suppose you start at a random vertex of some set $S$ that is not too large and you take a random edge out of this vertex. How likely are you to get out of $S$ ? If a random walk out of any vertex $s$ approaches the uniform distribution quickly, we would expect such a walk to avoid "getting stuck" in any set $S$. The following claim makes this intuition precise. The probability is taken over a pair of endpoints $(u, w)$ of a random directed edge of $G$.
Theorem 4. For every set $S$ of vertices,

$$
\operatorname{Pr}_{(u, w)}[u \in S \text { and } w \notin S] \geq\left(1-\lambda_{2}\right) \operatorname{Pr}_{u}[u \in S] \operatorname{Pr}_{w}[w \notin S] .
$$

To prove this theorem it is useful to describe the eigenvalues of $A$, the normalized adjacency matrix of $G$, in an alternative way. We look at the value of the expression $\mathbf{v} A \mathbf{v}^{\mathrm{T}}$ as $\mathbf{v}$ ranges over all vectors of norm 1 . We expand $\mathbf{v}$ in the basis of eigenvectors

$$
\mathbf{v}=\alpha_{1} \mathbf{v}_{1}+\cdots+\alpha_{n} \mathbf{v}_{n}
$$

where $\alpha_{1}^{2}+\cdots+\alpha_{n}^{2}=1$. Then

$$
\mathbf{v} A \mathbf{v}^{\mathrm{T}}=\left(\sum_{i=1}^{n} \alpha_{i} \mathbf{v}_{i}\right) A\left(\sum_{j=1}^{n} \alpha_{j} \mathbf{v}_{j}\right)=\sum_{i, j=1}^{n} \alpha_{i} \alpha_{j} \cdot \mathbf{v}_{i} A \mathbf{v}_{j}^{\mathrm{T}} .
$$

Since $\mathbf{v}_{i} A \mathbf{v}_{j}^{\mathrm{T}}=\lambda_{i} \mathbf{v}_{i} \mathbf{v}_{j}^{\mathrm{T}}=\lambda_{i}\left\langle\mathbf{v}_{i}, \mathbf{v}_{j}\right\rangle$ takes value $\lambda_{i}$ when $i=j$ and zero otherwise, we get

$$
\mathbf{v} A \mathbf{v}^{\mathrm{T}}=\alpha_{1}^{2} \lambda_{1}+\alpha_{2}^{2} \lambda_{2}+\cdots+\alpha_{n}^{2} \lambda_{n}
$$

It follows that $\mathbf{v} A \mathbf{v}^{\mathrm{T}}$ can be at most $\lambda_{1}$ and this value is attained when $\alpha_{1}=1$, namely when $\mathbf{v}=\mathbf{v}_{1}$. So we can describe $\lambda_{1}$ as

$$
\lambda_{1}=\max _{\|\mathbf{v}\|=1} \mathbf{v} A \mathbf{v}^{\mathrm{T}} .
$$

Similarly, we can describe $\lambda_{2}$ as the maximum of $\mathbf{v} A \mathbf{v}^{\mathrm{T}}$ but taken only over those $\mathbf{v}$ for which $\alpha_{1}=0$, namely those $\mathbf{v}$ that are perpendicular to $\mathbf{v}_{1}$. In our case $\mathbf{v}_{1}$ is parallel to $\mathbf{u}$ so we can write

$$
\lambda_{2}=\max _{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{u}} \mathbf{v} A \mathbf{v}^{\mathrm{T}}
$$

We will now give a probabilistic interpretation to the quantity $1-\lambda_{2}$. Fix $\mathbf{v}$ such that $\|\mathbf{v}\|=1$ and notice that

$$
\sum_{u, w=1}^{n} A_{u w}(\mathbf{v}(u)-\mathbf{v}(w))^{2}=\sum_{u, w=1}^{n} A_{u w} \mathbf{v}(u)^{2}+\sum_{u, w=1}^{n} A_{u w} \mathbf{v}(w)^{2}-2 \sum_{u, w=1}^{n} A_{u w} \mathbf{v}(u) \mathbf{v}(w) .
$$

Since each row and each column of $A$ adds up to one, each of the first two sums equals the sum of squares of the entries of $\mathbf{v}$, which is 1 . The third sum equals $\mathbf{v} A \mathbf{v}^{\mathrm{T}}$. Therefore we can write

$$
1-\lambda_{2}=\frac{1}{2} \min _{\|\mathbf{v}\|=1, \mathbf{v} \perp \mathbf{u}} \sum_{u, v=1}^{n} A_{u w}(\mathbf{v}(u)-\mathbf{v}(w))^{2}=\frac{1}{2} \min _{\mathbf{v} \perp \mathbf{u}} \frac{\sum_{u, v=1}^{n} A_{u w}(\mathbf{v}(u)-\mathbf{v}(w))^{2}}{\sum_{u=1}^{n} \mathbf{v}(u)^{2}}
$$

Since there are $d n$ directed edges of $G$, we get that $\sum A_{u w}(\mathbf{v}(u)-\mathbf{v}(w))^{2}=n \mathrm{E}_{(u, w)}\left[(\mathbf{v}(u)-\mathbf{v}(w))^{2}\right]$. We also have $\sum \mathbf{v}(u)^{2}=n \mathrm{E}_{u}\left[\mathbf{v}(u)^{2}\right]$. Therefore

$$
\begin{equation*}
1-\lambda_{2}=\frac{1}{2} \min _{\mathbf{v} \perp \mathbf{u}} \frac{\mathrm{E}_{(u, w)}\left[(\mathbf{v}(u)-\mathbf{v}(w))^{2}\right]}{\mathrm{E}_{u}\left[\mathbf{v}(u)^{2}\right]} \tag{5}
\end{equation*}
$$

Proof of Theorem 4. Let $S$ be any set of vertices, $\alpha=\operatorname{Pr}[u \in S]=|S| / n$ and set

$$
\mathbf{v}(u)= \begin{cases}1-\alpha, & \text { if } u \in S \\ -\alpha, & \text { if } u \notin S\end{cases}
$$

Notice that $\mathbf{v} \perp \mathbf{u}$, and that $(\mathbf{v}(u)-\mathbf{v}(w))^{2}$ is 1 when exactly one of $u$ and $w$ is in $S$ and the other is in $\bar{S}$, and 0 otherwise. In the first case we will say ( $u, w$ ) crosses $(S, \bar{S})$. Plugging into (5) we obtain

$$
1-\lambda_{2} \leq \frac{1}{2} \frac{\operatorname{Pr}_{(u, w)}[(u, w) \text { crosses }(S, \bar{S})]}{\mathrm{E}_{u}\left[\mathbf{v}(u)^{2}\right]}
$$

where

$$
\operatorname{Pr}_{(u, w)}[(u, w) \text { crosses }(S, \bar{S})]=2 \operatorname{Pr}[u \in S \text { and } w \notin S]
$$

and

$$
\mathrm{E}_{u}[\mathbf{v}(u)]^{2}=\alpha(1-\alpha)^{2}+(1-\alpha) \alpha^{2}=\alpha(1-\alpha)=\operatorname{Pr}[u \in S] \operatorname{Pr}[w \notin S] .
$$

## 4 Proof of Theorem 2

We now show how to deduce Theorem 2 from Theorem 1. Let $\Phi$ be a 2CSP with no restrictions on the number of occurrences of each variable. We show how to get a new instance $\Phi^{\prime}$ out of $\Phi$ where every variable occurs at most $d$ times.
Each variable $x_{i}$ in $\Phi$ gives rise to $n_{i}$ variables $x_{i 1}^{\prime}, \ldots, x_{i n_{i}}^{\prime}$ in $\Phi^{\prime}$. For each constraint $\phi_{i i^{\prime}}\left(x_{i}, x_{i^{\prime}}\right)$ in $\Phi$ we assign unique copies $x_{i j}^{\prime}, x_{i^{\prime} j^{\prime}}^{\prime}$ in $\Phi^{\prime}$ and add $d / 2$ copies of the constraint $\phi_{i i^{\prime}}\left(x_{i j}^{\prime}, x_{i^{\prime} j^{\prime}}^{\prime}\right)$ in $\Phi^{\prime}$. Finally, for every $i$ we fix a $d / 2$-regular graph $G_{i}$ on $n_{i}$ vertices with edge expansion $\lambda\left(G_{i}\right) \geq 1 / 2$ and introduce equality constraints $x_{i j}^{\prime}=x_{i j^{\prime}}^{\prime}$ for every edge $\left(i, i^{\prime}\right)$ of $G_{i}$. We will call these the equality constraints for $i$. We will talk about how to construct such an expander in the next two lectures.

If $\Phi$ has $m / 2$ constraints, then $\Phi^{\prime}$ will have $m$ variables and $d m$ constraints. If $\Phi$ is satisfiable, then $\Phi^{\prime}$ is clearly satisfiable. Now suppose we could find an assignment $x^{\prime}$ that satisfies a $1-\varepsilon$ fraction of the constraints of $\Phi^{\prime}$. Then the following claim allows us to convert $x^{\prime}$ into an assignment that satisfies a $1-18 \varepsilon$ fraction of the constraints of $\Phi$ :

Claim 5. If some assignment $x^{\prime}$ the violates at most an $\varepsilon$-fraction of contraints in $\Phi^{\prime}$, then the assignment $x$ where

$$
x_{i}=\text { plurality (most frequent) value among } x_{i 1}^{\prime}, \ldots, x_{i n_{i}}^{\prime}
$$

violates at most a $34 \varepsilon$ fraction of constraints in $\Phi$.
By Theorem 4, within every graph $G_{i}$

$$
|E(S, \bar{S})| \geq \frac{d|S||\bar{S}|}{4 n_{i}}
$$

for every subset $S$ of vertices in $G_{i}$, where $E(S, \bar{S})$ is the number of edges from a vertex in $S$ to a vertex outside $S$.

Let $S_{i}$ be the set of variables $x_{i j}^{\prime}$ that agree with the plurality value $x_{i}$. Let $\varepsilon_{i}$ be the fraction of the $d n_{i} / 4$ equality constraints for $i$ violated by the assignment $x^{\prime}$. We will argue that $\left|\overline{S_{i}}\right| \leq 8 \varepsilon_{i} n_{i}$ :

- If $\left|S_{i}\right|>n_{i} / 2$, then $\left|E\left(S_{i}, \bar{S}_{i}\right)\right| \geq d\left|\bar{S}_{i}\right| / 8$. Since all the equality constraints for $i$ between $S_{i}$ and $\bar{S}_{i}$ are violated by $x^{\prime}, \varepsilon_{i}\left(d n_{i} / 4\right) \geq\left|E\left(S_{i}, \bar{S}_{i}\right)\right|$, so $\left|\overline{S_{i}}\right| \leq 2 \varepsilon_{i} n_{i}$.
- If $n_{i} / 4 \leq\left|S_{i}\right| \leq n_{i} / 2$, then $\left|E\left(S_{i}, \bar{S}_{i}\right)\right| \geq d\left|S_{i}\right| / 8 \geq d n_{i} / 32$. Since all the equality constraints for $i$ between $S_{i}$ and $\bar{S}_{i}$ are violated by $x^{\prime}$, it follows that $\varepsilon_{i} \geq 1 / 8$, so $\left|\overline{S_{i}}\right| \leq n_{i} \leq 8 \varepsilon_{i} n_{i}$.
- If $\left|S_{i}\right|<n_{i} / 4$, then no value in $\Sigma$ is taken by more than a $1 / 4$-fraction of the $x_{i j}^{\prime} \mathrm{s}$, so there must exist some subset of values $\Sigma^{\prime} \subseteq \Sigma$ so the number of $x_{i j}^{\prime}$ taking values in $\Sigma^{\prime}$ is between $n_{i} / 4$ and $n_{i} / 2$. Just like in the previous case, we get $\left|\overline{S_{i}}\right| \leq n_{i} \leq 8 \varepsilon_{i} n_{i}$.

Now consider what happens in $\Phi^{\prime}$ when we replace the assignment $x^{\prime}$ with the plurality assignment $x_{\text {plur } i j}^{\prime}=x_{i}$ for every $j$. Replacing $x^{\prime}$ by $x_{\text {plur }}^{\prime}$ may cause the violation of at most ( $\left.d / 2\right)\left|\overline{S_{i}}\right|$ nonequality constraints for every $i$. If $x^{\prime}$ violates $\varepsilon d m$ constraints, $x_{\text {plur }}^{\prime}$ will then violate at most

$$
\varepsilon d m+\sum_{i=1}^{n}(d / 2)\left|\overline{S_{i}}\right| \leq \varepsilon d m+\sum_{i=1}^{n}(d / 2)\left(8 \varepsilon_{i} n_{i}\right)=\varepsilon d m+16 \sum_{i=1}^{n} \varepsilon_{i} d n_{i} / 4 \leq 17 \varepsilon d m
$$

constraints of $\Phi^{\prime}$. This is a $17 \varepsilon$-fraction of all the constraints in $\Phi^{\prime}$. Since exactly half the constraints in $\Phi^{\prime}$ are equality constraints, $x$ cannot violate more than a $34 \varepsilon$ fraction of constraints in $\Phi$.


[^0]:    ${ }^{1}$ This is not quite right: The correct way to say it is that for every index $i$ there exists an initial position for the particle that makes $\alpha_{i} \neq 0$.
    ${ }^{2}$ Ramanujan graphs are known to exist for every $d$ such that $d+1$ is a power of a prime larger than two.

